

# MEMS Technology : A Review

**Abstract**— Present work through light on the early research which has been carried out for the development of MEMS based sensors & Actuators. It carries subsequent applications of MEMS and discusses various recent technological innovations carried out. This work also describes the historical development of micro-electromechanical system (MEMS) sensor technology.

**Keywords-** MEMS, Sacling of MEMS Devices, Categorization and Applications of MEMS, Sensors, Actuators, MEMS Design & Fabrication Processes, Materials for MEMS.

## 1. About MEMS Technology:

Microelectromechanical systems (MEMS) (also written as micro-electro-mechanical, MicroElectroMechanical or microelectronic and microelectromechanical systems in the United States) is the technology of very small devices. It is also known as Micro machines, a term often used in Japan, or more broadly as Microsystems Technology (MST), in Europe.

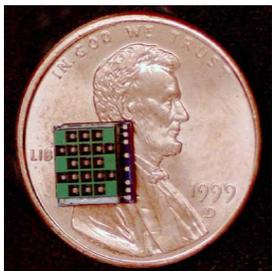


Figure 1 (a)

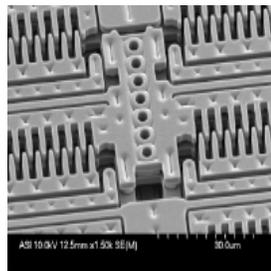


Figure 1 (b)



Figure 1 (c)



Figure 1 (d)

Figure 1 (a) represents the feature *Micro (small)* i.e. dimensional comparison, Figure 1 (b) represents the feature *Electro(electric components / functionality)*, Figure 1 (c) represents the feature *Mechanical(mechanical components / functionality)* and Figure 1 (d) represents the feature *Systems(integrated, system-like functionality)* [1]

Micro Electro Mechanical Systems or MEMS is a technology introduced by several researches to describe an emerging research field, where mechanical elements, like cantilevers or membranes, had been developed and manufactured at a scale closer to microelectronics circuit than to lathe machining.

Actually, what could link inkjet printer head, video projector DLP system, disposable bio-analysis chip and airbag crash sensor and many more - they are all MEMS devices & these devices share the presence of features below 100 µm that are not machined using standard machining like lathe but using other techniques globally called micro-fabrication technology. MEMS devices are quite different in comparison with electronic & microelectronics circuit as electronic circuits are inherently solid and compact structures, MEMS have holes, cavity, channels, cantilevers, membranes, etc, and, in some way, try to be like 'mechanical' parts. This has a direct impact on their manufacturing process. When MEMS are based on silicon, microelectronics process needs to be adapted to provide for thicker layer deposition, deeper

35 etching and to introduce special steps to free the mechanical structures. In other hand many more  
36 MEMS are not based on silicon and can be manufactured in polymer, in glass, in quartz or even  
37 in metals.

38 MEMS technology is separate and distinct from the hypothetical vision of molecular  
39 nanotechnology or molecular electronics. Microelectromechanical systems (MEMS) are small  
40 integrated devices or systems that combine electrical and mechanical components. These systems  
41 can sense, control, and activate mechanical processes on the micro scale, and function  
42 individually or in arrays to generate effects on the macro scale. The micro fabrication technology  
43 enables fabrication of large arrays of devices, which individually perform simple tasks, but in  
44 combination can accomplish complicated functions. MEMS are simultaneously a toolbox, a  
45 physical product, and a methodology, all in one [2]:

- 46 • It is a portfolio of techniques and processes to design and create miniature systems.
- 47 • It is a physical product often specialized and unique to a final application one can  
48 seldom buy a generic MEMS product at the neighborhood electronics store.
- 49 • “MEMS is a way of making things,” reports the Microsystems Technology Office of  
50 the United States DARPA [3]. These “things” merge the functions of sensing and  
51 actuation with computation and communication to locally control physical  
52 parameters at the microscale, yet cause effects at much grander scales.

53 MEMS are not about any one application or device, nor are they defined by a single fabrication  
54 process or limited to a few materials. They are a fabrication approach that conveys the  
55 advantages of miniaturization, multiple components, and microelectronics to the design and  
56 construction of integrated electromechanical systems. MEMS are not only about miniaturization  
57 of mechanical systems; they are also a new paradigm for designing mechanical devices and  
58 systems.

59 The functional elements of MEMS are miniaturized structures, sensors, actuators, and  
60 microelectronics, the most notable (and perhaps most interesting) elements are the microsensors  
61 and microactuators. Microactuators are appropriately categorized as “transducers”, which are  
62 defined as devices that convert energy from one form to another. In the case of microsensors, the  
63 device typically converts a measured mechanical signal into an electrical signal. Figure 2 (a)  
64 represents the functional elements of MEMS [4] and Figure 2 (b) represents the microsystem  
65 architecture of MEMS devices [1].

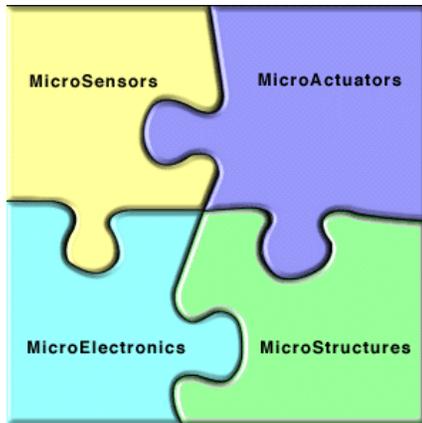


Figure 2 (a) [4]

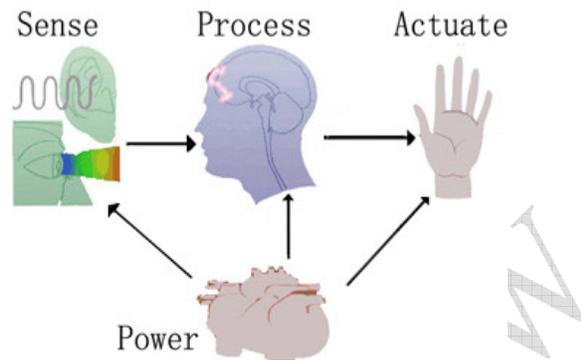


Figure 2 (b) [1]

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67

68 Microelectronic integrated circuits can be thought of as the "brains" of a system and MEMS  
 69 augments this decision-making capability with "eyes" and "arms", to allow Microsystems to  
 70 sense and control the environment. Sensors gather information from the environment through  
 71 measuring mechanical, thermal, biological, chemical, optical, and magnetic phenomena. The  
 72 electronics then process the information derived from the sensors and through some decision  
 73 making capability direct the actuators to respond by moving, positioning, regulating, pumping,  
 74 and filtering, thereby controlling the environment for some desired outcome or purpose [4].

75 Examples of MEMS device applications include inkjet-printer cartridges, accelerometers,  
 76 miniature robots, microengines, locks, inertial sensors, microtransmissions, micromirrors, micro  
 77 actuators, optical scanners, fluid pumps, transducers, and chemical, pressure and flow sensors.  
 78 New applications are emerging as the existing technology is applied to the miniaturization and  
 79 integration of conventional devices.

## 80 2. Advantages of MEMS Technology:

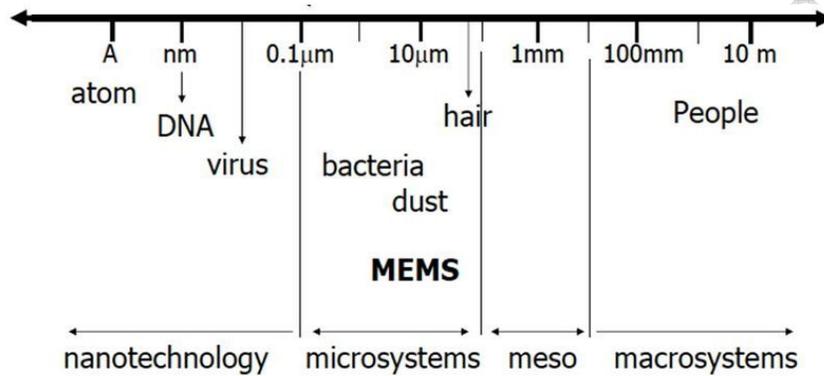
81 The development and fabrication of a MEMS component has a cost that cannot be  
 82 underestimated, but the technology has many of the possibility to bring unique benefits for the  
 83 mankind. The reasons that attract the researchers to use the MEMS technology can be classified  
 84 broadly in three classes [5]:

- 85 i. **Miniaturization of existing devices:** For example the production of silicon based  
 86 gyroscope which reduced existing devices weighting several kg and with a volume of  
 87  $1000 \text{ cm}^3$  to a chip of a few grams contained in a  $0.5 \text{ cm}^3$  package.
- 88 ii. **Using physical principles that do not work at larger scale:** A typical example is  
 89 given by the biochips where electric field are use to pump the reactant around the  
 90 chip. This so called electro osmotic effect based on the existence of a drag force in the  
 91 fluid works only in channels with dimension of a fraction of one mm, that is, at  
 92 micro-scale.
- 93 iii. **Developing tools for operation in the micro-world:** In 1986 H. Rohrer and G.  
 94 Binnig at IBM were awarded the Nobel prize in physics for their work on scanning  
 95 tunneling microscope. This work heralded the development of a new class of  
 96 microscopes (atomic force microscope, scanning near-field optical microscope etc.)

97 that shares the presence of micromachined sharp micro tips with radius below 50 nm.  
 98 This micro-tool was used to position atoms in complex arrangement, writing Chinese  
 99 character or helping verify some prediction of quantum mechanics.

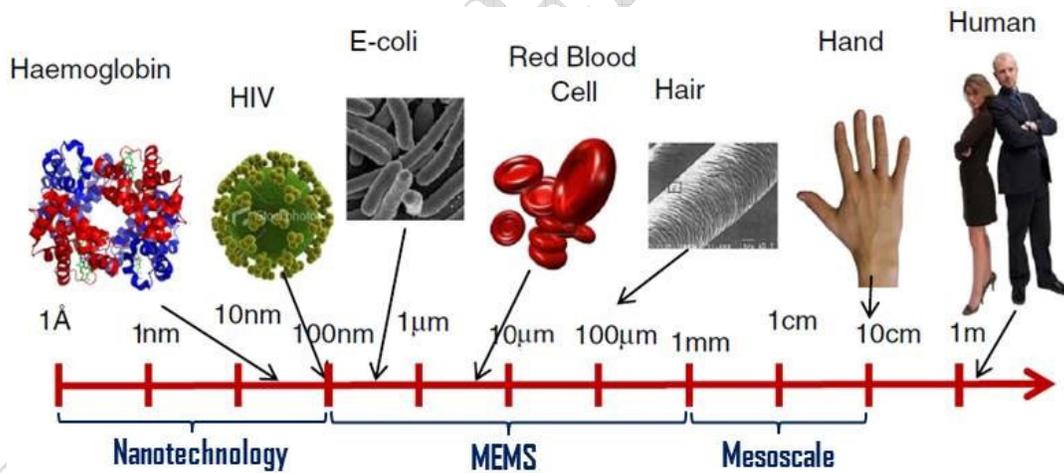
100 **3. Scaling of MEMS devices:**

101 MEMS are made up of components between 1 to 100 micrometres in size (i.e. 0.001 to 0.1 mm),  
 102 and MEMS devices generally range in size from 20 micrometres (20 millionths of a metre) to a  
 103 millimetre (i.e. 0.02 to 1.0 mm). Figure 2 & Figure 3 represents the size of MEMS devices with  
 104 compare to the existing world.



105

106 Figure 3 : Scale of things, in meters. [6]



107

108 Figure 4: Scale of things representing the region for dimensions of MEMS devices [1].

109 **4. History of MEMS:**

110 MEMS are tiny electro-mechanical devices that are built onto semiconductor chips and are  
 111 measured in micrometers. These devices are developed in the research labs during the 1980s.  
 112 MEMS devices began to materialize as commercial products in the mid-1990s.

113 Piezoresistive silicon strain gauges were introduced in the late 1950s by Kulite Semiconductor,  
114 Bell Lab's first licensee of patents on semiconductor piezoresistance reported in 1954 [7].  
115 Kulite's strain gauges represent some of the first commercially distributed  
116 microelectromechanical systems (MEMS) [8]. Although research on microsystems grew over the  
117 ensuing decades [9, 10] relatively few became widespread commercial products until  
118 manufacturing advances driven by the integrated circuits industry were widely available.

119 The history of MEMS is useful to illustrate its diversity, challenges and applications. The  
120 following list summarizes some of the key MEMS milestones [11, 12].

- 121 i. The invention of the transistor at Bell Telephone Laboratories in 1947 sparked a fast-  
122 growing microelectronic technology.
- 123 ii. Piezoresistive silicon strain gauges were introduced in the late 1950s by Kulite  
124 Semiconductor, Bell Lab's first licensee of patents on semiconductor piezoresistance  
125 reported in 1954 [7].
- 126 iii. In 1954 it was discovered that the piezoresistive effect in Ge and Si had the potential to  
127 produce Ge and Si strain gauges with a gauge factor (i.e., instrument sensitivity) 10 to 20  
128 times greater than those based on metal films. As a result, Si strain gauges began to be  
129 developed commercially in 1958.
- 130 iv. Kulite's strain gauges represent some of the first commercially distributed  
131 microelectromechanical systems (MEMS).
- 132 v. The first high-volume pressure sensor was marketed by National Semiconductor in 1974.  
133 This sensor included a temperature controller for constant-temperature operation.
- 134 vi. In 1982 "Silicon as a Mechanical Material" [13]. Instrumental paper to entice the  
135 scientific community – reference for material properties and etching data for silicon.
- 136 vii. Around 1982, the term micromachining came into use to designate the fabrication of  
137 micromechanical parts (such as pressure-sensor diaphragms or accelerometer suspension  
138 beams) for Si microsensors.
- 139 viii. During 1987-1988, a turning point was reached in micromachining when, for the first  
140 time, techniques for integrated fabrication of mechanisms (i.e. rigid bodies connected by  
141 joints for transmitting, controlling, or constraining relative movement) on Si were  
142 demonstrated.
- 143 ix. During a series of three separate workshops on microdynamics held in 1987, the term  
144 MEMS was coined.

## 145 5. Categorization of MEMS Devices:

146 MEMS devices can be categorized in following six distinct types based on the core application  
147 areas [2, 5, 6, 14]. These include:

- 148 1) **Sensors:-** These class of MEMS are fabricated to sense changes and act together  
149 with their environments. These classes of MEMS contain chemical, motion, inertia,  
150 thermal, and optical sensors.
- 151 2) **Actuators:-** These kind of devices are generated to supply power or to activate to other  
152 components. In MEMS, actuators are either driven electrostatically or thermally.

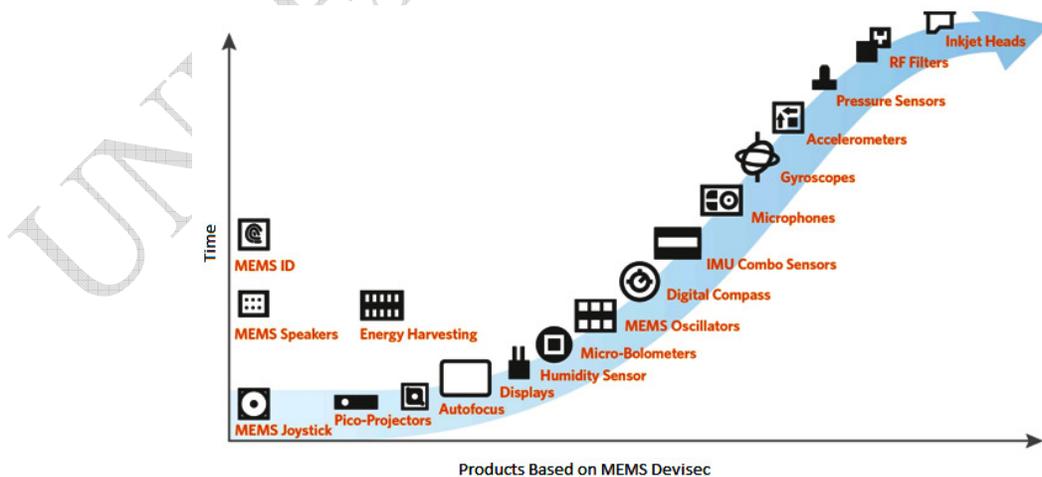
- 153 3) **RF MEMS:-** These devices are used to change or transmit high frequency or  
 154 Radio Frequency signals. Some distinctive devices include; metal contact switches,  
 155 shunt switches, tunable capacitors, antennas etc.
- 156 4) **Optical MEMS:-** These are fabricated to direct, reflect, filter, and/or amplify light.  
 157 These include optical switches and reflectors.
- 158 5) **Microfluidic MEMS:-** These are those devices which are designed to interact with fluid-  
 159 based environments. Some of the devices such as pumps and valves have been developed  
 160 to move, eject, and mix small volumes of fluid.
- 161 6) **Bio MEMS:-** Under this category devices are designed to interact with proteins,  
 162 biological cells, medical reagents, etc. and can be used for drug delivery or other in some  
 163 situation of medical analysis.

164 **6. Applications of MEMS Technology:**

165 Various advance, flexible and attractive features available with the MEMS technology thrust  
 166 their use in variety of applications. Below list and Figure 5 through light of various applications of  
 167 MEMS technology [5, 11, 15, 16, 17, 18].

1.	Automotive Applications	<ul style="list-style-type: none"> <li>• Air conditioning compressor sensor</li> <li>• Brake force sensors &amp; suspension control accelerometers</li> <li>• Fuel level &amp; vapour pressure sensors</li> <li>• Airbag sensors</li> <li>• "Intelligent" tyres</li> <li>• Vehicle Security Systems</li> <li>• Inertial Brake Lights</li> <li>• Headlight Leveling</li> <li>• Rollover Detection</li> <li>• Automatic Door Locks</li> <li>• Active Suspension</li> <li>• Vehicle Navigation Devices</li> <li>• Gyroscope &amp; Crash sensor</li> </ul>
2.	Consumer Electronics Applications	<ul style="list-style-type: none"> <li>• Disk drive heads</li> <li>• Inkjet printer heads</li> <li>• Projection screen &amp; televisions</li> <li>• Avionics pressure sensors</li> <li>• Mass data storage systems</li> <li>• Appliances</li> <li>• Sports Training Devices</li> <li>• Computer Peripherals</li> <li>• Active Subwoofers</li> </ul>

3.	Industrial Applications	<ul style="list-style-type: none"> <li>• Earthquake Detection and Gas Shutoff</li> <li>• Machine Health</li> <li>• Shock and Tilt Sensing</li> </ul>
4.	Communications Applications	<ul style="list-style-type: none"> <li>• Fibre-optic network components</li> <li>• RF Relays, switches and filters</li> <li>• Projection displays in portable communications devices and instrumentation</li> <li>• Voltage controlled oscillators (VCOs)</li> <li>• Splitters and couplers</li> <li>• Tuneable lasers</li> </ul>
5.	Defense / Military Applications	<ul style="list-style-type: none"> <li>• Munitions guidance</li> <li>• Surveillance</li> <li>• Arming systems</li> <li>• Embedded sensors</li> <li>• Data storage</li> <li>• Aircraft control</li> <li>• Tanks control</li> <li>• Equipment for Soldiers (Based on Energy Harvesting)</li> </ul>
6.	Medical / Biomedical / Microfluidics Applications	<ul style="list-style-type: none"> <li>• Blood pressure sensor</li> <li>• Muscle stimulators &amp; drug delivery systems</li> <li>• Implanted pressure sensors</li> <li>• Prosthetics</li> <li>• Miniature analytical instruments</li> <li>• Self powered Pacemakers (Based on Energy Harvesting)</li> </ul>



168

169

Figure 5 : Growth in MEMS application based products [17]

## 170 7. Material for MEMS Technology:

171 Following are the various materials used for production of MEMS devices [2, 5, 11, 12, 13, 18,  
172 23, 24, 25, 26, 27]:

- 173 • Silicon (Si) / poly-silicon (PolySi) [19].
- 174 • Silicon Oxide ( $\text{SiO}_2$  or  $\text{SiO}_x$ ) and/or silicate glass.
- 175 • Silicon Nitride ( $\text{Si}_3\text{N}_4$  or  $\text{Si}_x\text{N}_y$ ).
- 176 • Thin Metal Films of Gold, Nickel, Aluminum, Platinum, Palladium Chromium, titanium,  
177 Titanium-Tungsten and Permalloy™ ( $\text{Ni}_x\text{Fe}_y$ ).
- 178 • Indium-tin oxide (ITO).
- 179 • Quartz.
- 180 • Silicon Carbide and Diamond ( $\text{SiC}$  & Diamond) [22].
- 181 • GaAs.
- 182 • AlN.
- 183 • 92%  $\text{Al}_2\text{O}_3$ .
- 184 • Polyimide PMMA [poly(methylmethacrylate)], polypropylene, polyvinyl chloride,  
185 acrylic and other thermoplastics [20].
- 186 • Polymers [21].
- 187 • Piezoelectric ceramics e.g. Lithium niobate ( $\text{LiNbO}_3$ ) and barium titanate ( $\text{BaTiO}_3$ )
- 188 • Piezoelectric Composites (with lead & lead free composites).
- 189 • Glass and Fused Quartz Substrates.
- 190 • Gallium Arsenide and Other Group III-V Compound Semiconductors.
- 191 • Shape-Memory Alloys.
- 192 • Piezoelectric materials e.g. Lead Zirconate Titanate (PZT) a ceramic based on solid  
193 solutions of lead zirconate ( $\text{PbZrO}_3$ ) and lead titanate ( $\text{PbTiO}_3$ ), zinc oxide ( $\text{ZnO}$ ) and  
194 PVDF (Polyvinylidene-fluoride).

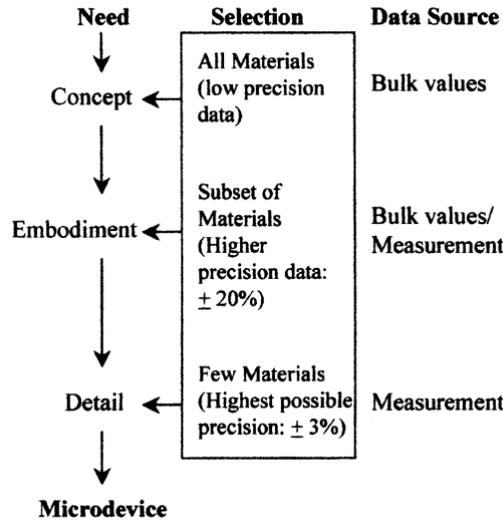
## 195 8. MEMS Design Processes:

196 The MEMS design process commence with defining requirements of the product for the MEMS  
197 device. These requirements are foundout through interviews and surveys of customers and users,  
198 as well as reviews of competitive products, and are defined in conditions of customer  
199 specifications. Quality function deployment (QFD) is a instrument that formalizes process of the  
200 product definition stage. Concepts with geometric and material property detail are analyzed for  
201 forecasted performance and the design can be reshaped & refined based on results from  
202 analytical, numerical, or finite element models using data from in-house processes or the  
203 literature. Models for the general performance of commonly available classes of MEMS  
204 transducers are available elsewhere [28–30].

205 A lot of examples express the benefits of using design methods [31–34], and design methods are  
206 commonly applied in industries from automotive to aerospace to semiconductors. Yet, design  
207 methodologies have less frequently been applied to MEMS products [35,36].

## 208 9. Process Selection for MEMS:

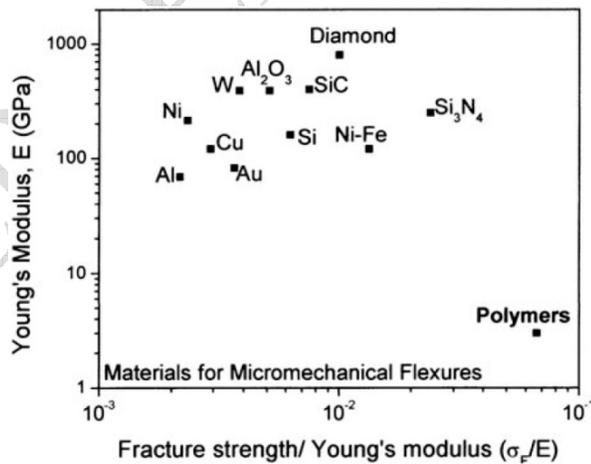
209 The list of materials used for MEMS continues to raise, while CMOS compatible materials and  
 210 silicon still include a large portion of commercial products for their noticeable compatibilities  
 211 with electronics and characteristics for micromachining. Srikar and Spearing [37] classified five  
 212 materials indices to aid in materials selection. For their resonator case study these are based on  
 213 attributes including mass, stiffness, inertial load, deflection, and frequency and are related to  
 214 materials properties.



215

216 Figure 6 : The quality of materials data required for design increases as the design process  
 217 progresses, First appearing in Srikar and Spearing [37]

218



219

220 Figure 7 : Micromechanical flexures require a large ratio of fracture strength to Young's  
 221 modulus, First appearing in Srikar and Spearing [37].

222

223 MEMS devices comprises of major (structural) materials and minor (dielectric, interconnect)  
 224 materials [38]. MEMS processes often also employ secondary materials (not contributing to the  
 225 structure) as sacrificial materials in the manufacturing flow. Characteristic of concern to the  
 226 design process comprise the material properties, net shape of the device together with surface

227 roughness and tolerances, the processing restraint on pressure, temperature, and materials  
228 interfaces/compatibilities.

## 229 **10. MEMS Fabrication Technologies:**

230 This segment of the paper presents a summary of the key processes and process instructions  
231 usually employed in the deposition of semiconductor and dielectric thin films used in the  
232 production of microelectromechanical systems (MEMS). These methods contain chemical vapor  
233 deposition, epitaxy, physical vapor deposition, atomic layer deposition, and spin-on techniques.  
234 The materials used in this section include silicon and its oxide, nitride, and carbide derivatives,  
235 silicon–germanium, diamond and diamondlike carbon, III-V semiconductors, aluminum oxide,  
236 and other notable semiconductor and dielectric materials used as structural, sacrificial, and  
237 passivation layers. An explanation of the oxidation process, including a careful development of  
238 the Deal–Grove model & the data required to compute oxidation times and thicknesses can be  
239 found in nearly any advanced undergraduate or graduate text on silicon VLSI fabrication  
240 technology, including two notable texts commonly used by MEMS process engineers [39–41].

241 The process method presented in this section of the paper largely comes from publications that  
242 report not only processing details, but also key material properties of importance to MEMS that  
243 result from the reported processes. Whenever possible, the references included in this section are  
244 papers that are readily available via commonly used electronic databases such as IEEE Xplore™  
245 and ScienceDirect™ so as to aid the reader in gathering more detailed information than can be  
246 practically presented herein.

### 247 **10.1 Thermal Conversion:**

248 Silicon’s place as the leading semiconductor in modern IC technology can be attributed to the  
249 passivating oxide that can be readily formed on its surface. Normally referred by the process  
250 engineers as “silicon oxide” this material is theoretically “silicon dioxide” in chemical  
251 composition. Silicon dioxide ( $\text{SiO}_2$ ) physically forms on the surface of Si by a method known as  
252 oxidation. Oxidation is a thermally driven translation process that occurs over a very broad range  
253 of temperatures, together with ambient conditions. If developed at room temperature, the  
254 material is known as a “native oxide” and has a thickness of approximately 1–2 nm.

255 For MEMS functions, much thicker oxides (hundreds of nm to several microns) are  
256 characteristically required, demanding the need for processing tools to construct such films. Of  
257 all the thin-film growth processes used in MEMS, oxidation of silicon is one of the most  
258 uncomplicated due to the simplicity of the process. Dissimilar to the other materials commonly  
259 used in MEMS, thermal  $\text{SiO}_2$  films can only be developed on silicon substrates, thereby  
260 restraining their applicability in multilayered structures. That being said, thermal oxidation is not  
261 limited to single crystalline Si wafers, but can also be executed to produce  $\text{SiO}_2$  on polysilicon  
262 films, for as long as the materials under the polysilicon layer can abide the high temperatures  
263 connected with the oxidation process. Thermal oxides can also be developed on silicon carbide  
264 substrates, even though at a much lower rate than for silicon [42].

265 Desai explained a process to produce silicon nanoporous membranes using a thermal oxide as a  
266 sacrificial material for pore formation [43]. The process engages the growth of a thin (20–100

267 nm) thermal oxide on a boron-doped Si substrate that is photolithographically patterned and  
268 etched to form an array of vias.

## 269 **10.2 Chemical Vapor Deposition:**

270 Chemical vapor deposition (CVD) process is the most broadly used resources to deposit  
271 semiconductor and dielectric materials employed in MEMS technology. In general CVD is a  
272 method where a thin film is created by the deposition of vapor-phase components onto a heated  
273 substrate. CVD has several key characteristics that make it the dominant deposition  
274 method for semiconductors and dielectrics in MEMS. The commonly available types of CVD are  
275 as follows:

- 276 a) Low Pressure Chemical Vapor Deposition (LPCVD).
- 277 b) Plasma-Enhanced Chemical Vapor Deposition (PECVD).
- 278 c) Atmospheric Pressure Chemical Vapor Deposition (APCVD).
- 279 d) Hot Filament Chemical Vapor Deposition (HFCVD).
- 280 e) Microwave Plasma Chemical Vapor Deposition (MPCVD).

281 The microstructure of polysilicon thin films consists of a collection of small grains whose  
282 microstructure and orientation is a function of the deposition conditions [44]. For typical LPCVD  
283 processes (e.g., 200 mtorr), the amorphous-to-polycrystalline transition temperature is about  
284 570°C, with polycrystalline films deposited above the transition temperature. At 600°C, the  
285 grains are small and equiaxed, whereas at 625°C, the grains are large and columnar [44]. The  
286 inclusion of boron generally increases the deposition rate of polysilicon relative to undoped  
287 films, whereas phosphorus reduces the rate [45]. In SiO<sub>2</sub> doping is commonly used to produce  
288 conductive films for electrostatic devices, but has also been used to create polysilicon-based  
289 piezoresistive strain gauges, with gauge factors as high as 15 having been reported [46]. The  
290 density of polysilicon has been reported as 2.25 – 2.33 g/cm<sup>3</sup> under varied conditions [46]. The  
291 refractive index of polysilicon has been reported as 3.22 – 3.40 also under varied conditions [47].  
292 The fracture toughness of polysilicon has been measured to be  $1.2 \pm 0.2 \text{ MPa}\sqrt{\text{m}}$  [48].

293 The MUMPS™ process is a popular multiuser process whose design guidelines can be found in  
294 [49]. Although the exact growth conditions of these films are not typically published in the  
295 literature, it has been reported that the films are deposited using silane gas at a temperature of  
296 580°C and pressure of 250 mtorr [50]. High cycle fatigue testing of these films was explored in  
297 [51]. The complete design guidelines for this process can be found in [52]. The dielectric  
298 constant of LPCVD SiO<sub>2</sub>, commonly referred to as LTO or low temperature oxide due to its low  
299 deposition temperature when compared to thermal oxidation, is 4.3. The dielectric strength of  
300 LTO is about 80% of that for thermal oxide [53].

301 PSG films are useful as sacrificial layers because they generally have higher etching rates in HF  
302 than LTO films. PSG is compatible with LPCVD polysilicon deposition conditions, thus  
303 enabling its use in multilayered polysilicon surface micromachining processes [54]. The residual  
304 stress in stoichiometric Si<sub>3</sub>N<sub>4</sub> is large and tensile, with a magnitude of about 1 GPa [55]. Thin  
305 stoichiometric Si<sub>3</sub>N<sub>4</sub> films have been used as mechanical support structures and electrical  
306 insulating layers in piezoresistive pressure sensors [56]. Nearly stress-free films can be deposited  
307 using a SiH<sub>2</sub>Cl<sub>2</sub>-to-NH<sub>3</sub> ratio of 6:1, a deposition temperature of 850°C and a pressure of 500

308 mtorr [57]. A detailed study concerning the influence of the Si-to-N ratio on the residual stress in  
309 silicon nitride films can be found in [58, 59]. The composition of low-stress nitride has been  
310 reported to be  $\text{Si}_{1.0}\text{N}_{1.1}$  [60].

311 The strength of silicon nitride films also varies with the Si-to-N ratio. For example, the tensile  
312 strength has been reported to be 6.4 GPa for stoichiometric films and 5.5 GPa for silicon-rich  
313 films [61]. A similar decrease in fracture toughness is observed for silicon-rich silicon nitride  
314 with an upper bound to be  $<14 \text{ MPa}\sqrt{\text{m}}$  for stoichiometric nitride and  $1.8 \text{ MPa}\sqrt{\text{m}}$  for low-stress  
315 nitride [62]. Reference [63] describes a study to characterize the mechanical properties of  
316 stoichiometric  $\text{Si}_3\text{N}_4$  using 70–80 nm thick membranes. Load-deflection testing was then used  
317 to characterize the films, yielding a biaxial modulus of 288 GPa, a fracture stress of 10.8–11.7  
318 GPa, and a residual stress of 1040 MPa [63]. Surface micromachined structures have also been  
319 used to determine the Young's modulus of low-stress nitride films [64].

320 Germanium (Ge) and silicon–germanium (SiGe) are of interest to the MEMS community  
321 because of the low temperatures required to deposit polycrystalline films, making them  
322 potentially compatible with Si CMOS structures in integrated MEMS devices. Polycrystalline Ge  
323 (poly-Ge) films can be deposited by LPCVD at temperatures as low as 325°C on Si, Ge, and  
324 silicon–germanium (SiGe) substrate materials [65]. The mechanical properties of poly-Ge are  
325 comparable with polysilicon, with a Young's modulus of 132 GPa and a fracture stress ranging  
326 between 1.5 and 3.0 GPa [66].

327 Deposition temperatures range between 450°C for conventional LPCVD [67] and 625°C for  
328 rapid thermal CVD (RTCVD) [68]. In situ boron doping can be performed at temperatures as  
329 low as 450°C [67]. Sedky [69] showed that the deposition temperature of conductive films doped  
330 with boron could be further reduced to 400°C if the Ge content was kept at or above 70%. Sedky  
331 [70] showed that the microstructure, film conductivity, residual stress, and residual stress  
332 gradient are related to the concentration of Ge in the material. Franke [71] produced in situ  
333 boron-doped films with residual compressive stresses as low as 10 MPa. PolySiGe has a lower  
334 thermal conductivity than Si, making it a well-suited alternative to polysilicon for thermopiles  
335 [72]. Poly-SiGe films exhibit a residual stress that can either be moderately tensile or moderately  
336 compressive depending on the Ge content and deposition temperature [70, 73].

337 Polycrystalline SiC (poly-SiC) is a more versatile material for SiC MEMS than its single-  
338 crystal counterparts because poly-SiC is not constrained to single-crystalline substrates but can  
339 be deposited on a variety of materials, including polysilicon,  $\text{SiO}_2$ , and  $\text{Si}_3\text{N}_4$ . Commonly  
340 used deposition techniques include LPCVD [74, 75, 76] and APCVD [77, 78].

### 341 **10.3 Epitaxy:**

342 Epitaxy is a special case of thin-film growth where a single-crystalline thin-film is grown upon a  
343 single-crystalline substrate such that the crystalline structure of the film is formed using the  
344 crystalline structure of the substrate as a template. Most epitaxial semiconductor films are grown  
345 by a process called vapor phase epitaxy (VPE). Unlike conventional LPCVD processes that  
346 typically have deposition rates less than 10 nm/min, epitaxial processes have deposition rates on  
347 the order of 1  $\mu\text{m}/\text{min}$  [79].

348 The Young's modulus of epi-poly measured from micromachined test structures is comparable  
349 with LPCVD polysilicon [80]. The fact that epi-poly does not readily nucleate on SiO<sub>2</sub> surfaces  
350 has recently been exploited in a selective growth process for patterning epi-poly films [81]. For  
351 designs that require electrical isolation from the substrate, 3C-SiC devices can be made directly  
352 on SOI substrates [82] or by wafer bonding and etchback, such as the capacitive pressure sensor  
353 developed by Young et al. [83]. High-quality 3C-SiC films can be grown on Si substrates by  
354 molecular beam epitaxy [84], although the process is much less commonly used than APCVD or  
355 LPCVD.

#### 356 **10.4 Physical Vapor Deposition:**

357 Physical vapor deposition (PVD) is a process by which a physical mechanism is the primary  
358 means by which a film-producing vapor is generated (in contrast to CVD where gaseous  
359 chemical precursors are used). PVD techniques have been developed to produce Si thin films  
360 [85, 86] as a low temperature alternative to LPCVD polysilicon and PECVD amorphous silicon.  
361 Sputtered SiC films can be deposited by RF magnetron sputtering of a SiC target [87] or by dual  
362 source DC magnetron sputtering of Si and graphite targets [88]. Bhatt and Chandra [89] have  
363 developed a sputtering process suitable for the production of micromachined SiO<sub>2</sub> structures.

#### 364 **10.5 Atomic Layer Deposition:**

365 Atomic layer deposition (ALD) is a variant of CVD where compound materials, typically binary  
366 compounds, are formed on a substrate surface by sequential exposure to two highly reactive  
367 vapor-phase chemical precursors. Hoivik et al. showed that alumina films deposited by ALD can  
368 overcoat all exposed surfaces of a released surface micromachined polysilicon cantilever, albeit  
369 with a small variation in thickness between the top and bottom surfaces of the beam [90]. Yang  
370 and Kang investigated the chemical durability of ALD alumina films in aqueous and vapor phase  
371 HF and found that the films were much more chemically stable when exposed to vapor phase HF  
372 than when exposed to aqueous solutions [91].

#### 373 **10.6 Spin-On Films:**

374 Spin-on dielectrics, such as siloxane-based spin-on glass (SOG), have become a mainstay  
375 material of backend processing in IC fabrication because the material can be conveniently  
376 deposited and processed at reasonable temperatures, and it retains acceptable dielectric properties  
377 for surface passivation and mechanical protection of electronic interconnects. Although the  
378 processing conditions vary depending on the source of SOG, the following sequence is  
379 representative of a common SOG known as Honeywell Accuglass 512B<sup>TM</sup> [92]. SOG has been  
380 used as a thick film sacrificial molding material to pattern thick polysilicon films [93]. The cured  
381 SOG films were completely compatible with the LPCVD process and posed no contamination  
382 risk. SOG has also been used as a structural material in high-aspect-ratio channel plate  
383 microstructures [94].

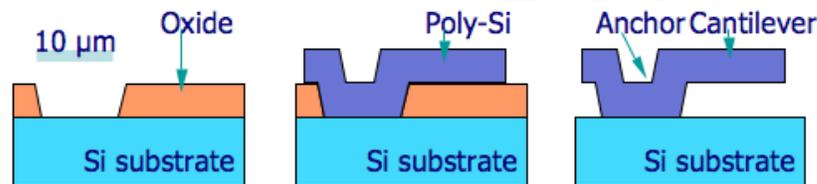
#### 384 **10.7 Bulk Micromachining:**

385 The oldest micromachining technology is bulk micromachining. This technique involves the  
386 selective removal of the substrate material in order to realize miniaturized mechanical  
387 components. Bulk micromachining can be accomplished using chemical or physical means, with

388 chemical means being far more widely used in the MEMS industry. A widely used bulk  
389 micromachining technique is chemical wet etching, which involves the immersion of a substrate  
390 into a solution of reactive chemical that will etch exposed regions of the substrate at measurable  
391 rates.

### 392 **10.8 Surface micromachining:**

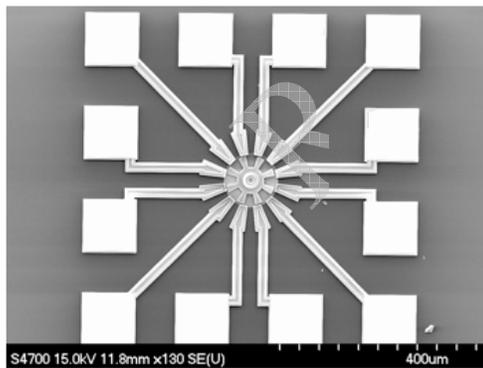
393 Surface micromachining is another very popular technology used for the fabrication of MEMS  
394 devices. There are a very large number of variations of how surface micromachining is  
395 performed, depending on the materials and etchant combinations that are used. However, the  
396 common theme involves a sequence of steps starting with the deposition of some thin-film  
397 material to act as a temporary mechanical layer onto which the actual device layers are built;  
398 followed by the deposition and patterning of the thin-film device layer of material which is  
399 referred to as the structural layer; then followed by the removal of the temporary layer to release  
400 the mechanical structure layer from the constraint of the underlying layer, thereby allowing the  
401 structural layer to move. An illustration of a surface micromachining process is shown in  
402 Figure :8, wherein an oxide layer is deposited and patterned.



403

404

Figure: 8 - Illustration of a surface micromachining process.



405

406

Figure: 9 (a)

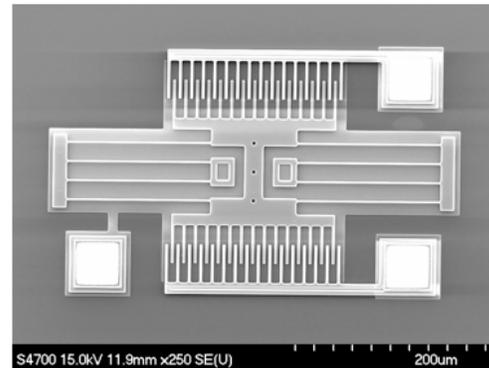


Figure: 9 (b)

407 Figure: 9 (a) represents Polysilicon micromotor & Figure: 9 (b) represents Polysilicon resonator  
408 structure fabricated using a surface micromachining process.

### 409 **10.9 The Lithography Module:**

410 Typically lithography is performed as part of a well-characterized module, which includes the  
411 wafer surface preparation, photoresist deposition, alignment of the mask and wafer, exposure,  
412 develop and appropriate resist conditioning. The lithography process steps need to be

413 characterized as a sequence in order to ensure that the remaining resist at the end of the modules  
414 is an optimal image of the mask, and has the desired sidewall profile.

### 415 **10.10 Etching Processes:**

416 In order to form a functional MEMS structure on a substrate, it is necessary to etch the thin films  
417 previously deposited and/or the substrate itself. In general, there are two classes of etching  
418 processes:

- 419 a) Wet etching where the material is dissolved when immersed in a chemical solution.
- 420 b) Dry etching where the material is sputtered or dissolved using reactive ions or a vapor  
421 phase etchant

### 422 **11. CHALLENGES & REQUIREMENTS:**

423 Following are the various challenges associated with MEMS technology[14, 95, 96, 97, 98]:-

- 424 a) **Access to Fabrication:** Most of the companies who wish to investigate the potential of  
425 MEMS have very few options for manufacturing devices, and have less expertise in  
426 microfabrication technology. A mechanism giving smaller organization responsive and  
427 affordable access to MEMS is essential.
- 428 b) **Packaging:** MEMS packaging is more challenging than IC packaging due to  
429 diversity of MEMS devices and the requirement that many of these devices be in  
430 contact with their environment. Most companies find that packaging is the single  
431 most expensive and time consuming task in their overall product development program.
- 432 c) **Fabrication Knowledge Required:** Currently the designer of MEMS device require a  
433 high level of fabrication knowledge in order to create a successful design. MEMS  
434 devices require a dedicated research effort to find a suitable process sequence for  
435 fabricating it.

### 437 **12. CONCLUSION**

438 MEMS technology has a potential to become an upcoming technological revolution of  
439 miniaturization. Availability of Micromachining fabrication process and MEMS technologies are  
440 influential utensils for enabling the miniaturization of MEMS based sensors, actuators and  
441 Industrial / Commercial / Bio-Medical systems. With the reductions in cost price and augment in  
442 performance of microsensors, microactuators and microsystems will enable the society.

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